

# Design of a two-stage Broadband Stable Power Amplifier for Low Power Wireless Telemetry Systems using 90 nm CMOS Technology

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**Abstract**—This paper presents the design of a 0.9-1.25 GHz two-stage power amplifier using 90 nm CMOS Cadence Virtuoso for a wireless telemetry system. The system utilizes radio-frequency (RF) communication to remotely measure and transmit data for monitoring patients vital signs (pulse and respiration). The design aims to balance low power consumption with performance parameters (gain, efficiency, output power, linearity, bandwidth, and thermal stability). The proposed amplifier consists of two stages, achieving strong impedance matching with  $S_{11} = -13.14$  dB and  $S_{22} = -12.66$  dB. It provides a forward transmission coefficient ( $S_{21}$ ) of 21.90 dB to a 50  $\Omega$  load at an operating frequency of 1.097 GHz with a supply voltage of 1.2 V. Within the specified bandwidth, the gain is more significant than 15 dB. Total power consumption is 153.1 mW. The amplifier exhibits a Gain-Bandwidth Product of 18.06 dB.GHz, which is a standard metric indicating its gain-versus-bandwidth trade-off. The stability factors ( $Kf > 1$  &  $B1f > 0$ ) confirm the unconditional stability. The design successfully meets the specified requirements for the intended wireless biomedical telemetry application.

**Index Terms**—Power amplifier, Stability factor, Wireless Telemetry, Power consumption, Bodway Factor.

## I. INTRODUCTION

An electronic device intended to boost an electrical signal's strength is called a power amplifier (PA). Wireless communication systems, radio receivers, and audio systems are just a few of the various uses for PAs. With the growing demand for higher data rates, improved signal integrity, and reduced power consumption, particularly in applications such as wireless communications, audio processing, and radar systems, the design of efficient and high-performance PAs has become critically important. The input signal's power is raised sufficiently in the PA. A PA is the last link in an amplifier chain and is made to drive loads directly, in contrast to voltage/current amplifiers. The basic signal flow and functional components of a PA system are illustrated in Fig.1, where a small-signal amplifier is followed by a PA driven by a DC supply to generate RF output.

Since one of the transistor nodes is AC grounded, there are three possible configurations for the single transistor arrangement that is typically used to create PAs. Fig.2 illustrates these

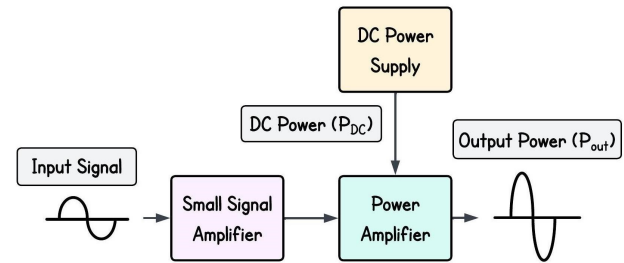


Fig. 1: Signal flow of a Power Amplifier system

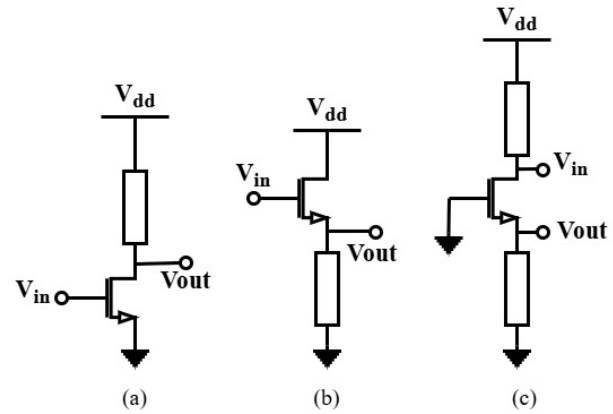


Fig. 2: Single transistor amplifier (a) Common Source; (b) Common drain; (c) Common Gate

options highlighting their input, output, and supply connections. PAs are designed to deliver high efficiency, reliability, and performance across a variety of operating conditions. Tailored to the specific application needs, different topologies and configurations are used to optimize the factors (efficiency, linearity, gain flatness, and output power). Transistor-based PAs are widely used due to their versatility and effectiveness in meeting diverse requirements. However, several challenges arise in the design and operation of PAs. For instance, two-stage op-amps limit the gain and output voltage swing, which impacts performance and reduces the unity gain bandwidth [1].

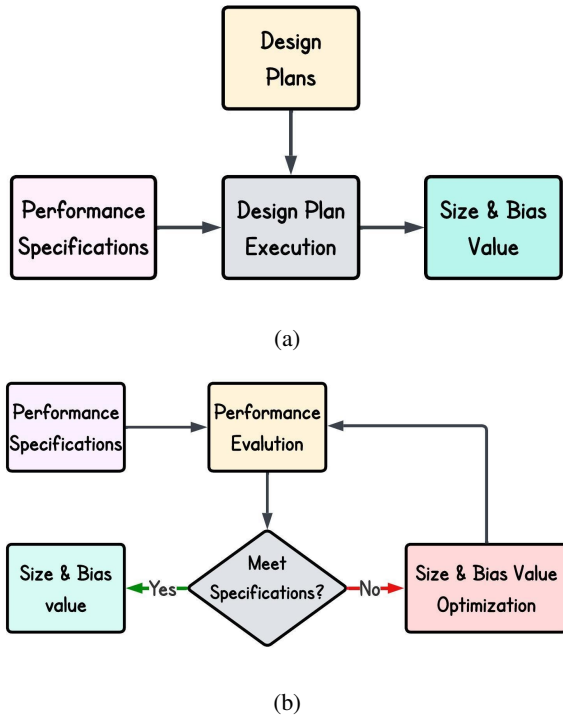


Fig. 3: Fig. 3. Synthesis of the analog circuit (a) on knowledge, (b) on optimization.

Additionally, extra components of matching circuits reduce the gain flatness, and parasitic may cause oscillations [2]. Short-channel devices also struggle to maintain transconductance as drain current increases, complicating PA design [3]. Another challenge is the design of linear mixers with low voltage due to the scalability of the underlying technology [4]–[6]. The low breakdown voltage and considerable substrate loss of different technologies limit the PA [7]. Despite these limitations, a significant progress across different bands(V,Ka) has been done through CMOS and BiCMOS technologies utilizing Wilkinson power combining [8] and multi-stage LNA offers high gain and wideband coverage [9]. A dual-band PA operates using a tunable stub for band switching [10], while CMOS PA achieves also high gain with stable operation [11]. Conflicting performance requirements make PA design complex, requiring careful choices in device selection, biasing, topology, and load matching. To address the challenges, advanced amplifier topologies, adaptive biasing techniques, linearization methods, and the use of different technologies have been explored. These innovations contribute to addressing the critical trade-offs between performance parameters. In this paper, a two-stage Common Gate-Common Source (CG-CS) PA is designed using a superimposed staggered tuning approach, targeting a wireless telemetry system for patient monitoring and data transmission.

The architecture employs a Common-Gate (CG) input stage, which provides wideband input matching, followed

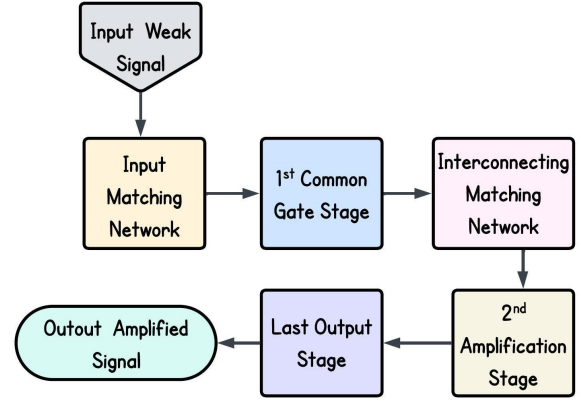


Fig. 4: Block diagram of proposed PA

by a Common-Source (CS) output stage that enhances gain. The configuration ensures dependable wireless data transfer between medical sensors and monitoring units. Fig.3 illustrates the design technique, where Fig.3(a) refers to sizing and biasing the amplifier based on analytical models and designer expertise to achieve the targets and Fig.3(b) shows those values are iteratively adjusted using simulation-based optimization tools until the specifications are met. By integrating a knowledge-driven, rule-based design with automated refinement, the methodology produces a robust initial design and delivers precise final optimization [12]. Fig.4 represents the typical structure of the proposed PA, where a weak signal is boosted through successive stages and delivers high power to the load effectively converting a small signal into strong output.

## II. METHODOLOGY

### A. Design of proposed PA

Even though subthreshold biasing provides higher  $(\frac{g_m}{I_D})$  than strong inversion, wideband PA design becomes very difficult when analog and RF circuits operating in the subthreshold zone exhibit increased thermal noise, worse bandwidth, and poor linearity. When building a PA, several important factors (such as frequency range, gain, noise figure, input/output impedance, and power consumption) must be considered to ensure optimal performance. The suggested PA (shown in Fig.5) provides moderate bandwidth and modest gain. The operational frequency range of 0.9 GHz to 1.25 GHz is selected first. To make the design more suitable for the application needing flawless frequency performance and input impedance matching, a CG stage is employed in the first stage. Because of its high output impedance, low input impedance, enhanced frequency response, and efficient isolation between input and output stages, the CG circuit is preferred in PA designs.  $L_1$  is used to match the amplifier to the 50  $\Omega$  source impedance.

A second amplification CS stage is typically added to the PA to boost gain. Because this stage helps to maintain

signal integrity and makes the amplifier suitable for several applications requiring broad frequency coverage. Additionally, it can boost the reflection coefficient, reduce distortion, and enhance overall performance, particularly in high-frequency applications where signal integrity is crucial. The second stage is added using staggered tuning to boost gain and bandwidth. The design illustrates the usage of  $L_5$  and  $C_{gs2}$  to create a tank circuit at  $M_2$ 's the source terminal. After that, an interstage matching T network is developed between the first and second stages. Finally, the buffer circuit is included, and the output-matching T network is added to improve the output return loss. A  $50\ \Omega$  load impedance is matched utilizing the T network created by  $L_7$ ,  $C_2$  and  $C_3$ .  $M_5$  allows the on-wafer characterization of PA using a  $50\ \Omega$ -based setup. The bias voltage  $V_b$  of  $M_1$  is biased at 0.83 V. Table-I lists all key components used in the PA, along with their value, providing a clear overview of the circuit's design and the sizing of each element.

### B. Schematic Diagram of PA

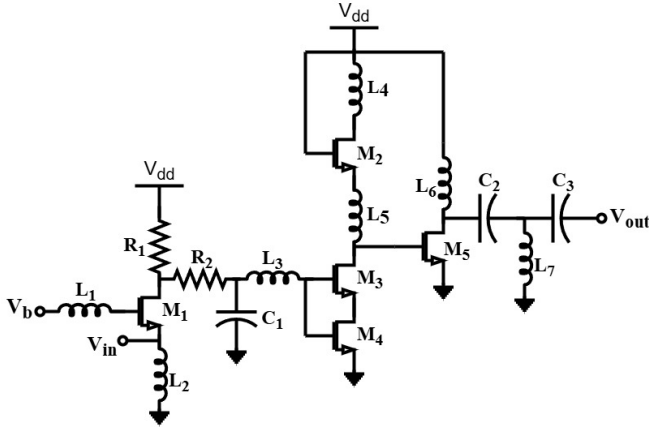


Fig. 5: Schematic of proposed wideband PA

## III. PERFORMANCE ANALYSIS

PA's input matching is achieved by setting  $g_m$ . The small-signal equivalent circuit for the impedance calculation is shown in Fig.6. A CG input stage (Fig.6 a and c) serves as a current buffer with low input impedance and small Miller feedback, ideal for impedance matching and wideband operation. It drives a CS middle stage (Fig.6 b and d), which provides high voltage gain but its bandwidth is limited by Miller capacitance ( $C_{gd}$ ). The cascade structure effectively combines current buffering and voltage amplification for achieving both wide bandwidth and significant gain.

### A. Input Matching

Now, the impedance as perceived from the source terminal,

$$Z_{in} = j\omega(L_1 + L_2) + \frac{1}{j\omega C_{gs1}} + \frac{g_{m1}L_1}{C} \quad (1)$$

TABLE I: Component Values for the PA

Aspect ratio	$\left(\frac{W}{L}\right)_{M1}$	$\left(\frac{W}{L}\right)_{M2}$	$\left(\frac{W}{L}\right)_{M3}$	$\left(\frac{W}{L}\right)_{M4}$
	$\frac{25\mu}{100n}$	$\frac{349.02\mu}{100n}$	$\frac{91\mu}{100n}$	$\frac{100\mu}{100n}$
	$\left(\frac{W}{L}\right)_{M5}$			
	$\frac{135\mu}{100n}$			
Inductor (nH)	$L_1$	$L_2$	$L_3$	$L_4$
	3	29.5	37	1.5
	$L_5$	$L_6$	$L_7$	
	115	110	91	
Capacitor (fF)	$C_1$	$C_2$	$C_3$	
	138	$3.8 \times 10^{15}$	$1.18 \times 10^5$	
Resistor ( $\Omega$ )	$R_1$	$R_2$		
	7	30		

$$Z_{in2} = R_g \parallel j\omega L_3 \quad (2)$$

where,  $R_g$  is the gate resistance,  $g_{m1}L_1$  is the transconductance of  $M_1$ ,  $L_3$  is the inductor at the input side of the 2nd stage, and  $j\omega L_3$  represents the inductive reactance. At high frequencies,  $L_3$  dominates, making  $Z_{in2}$  inductive. The output impedance at  $V_{out}$  depends on,

$$Z_{out} = r_{o2} \parallel j\omega L_5 \quad (3)$$

where  $r_{o2}$  is the output resistance of  $M_2$ ,  $L_5$  is the inductor connected to the drain. Since inductors have high impedance at high frequencies,  $Z_{out}$  is large, which is beneficial for power amplification.

### B. Gain Analysis

Equation (4) emphasizes how important the network's Quality Factor (QF) is in connection to the amplifier's gain.

$$A_{v1} = (2\pi f_L)g_{m1}Q_1 \quad (4)$$

$$A_{v2} = g_{m3} \left( \frac{1}{\omega L_5} \parallel \frac{1}{g_{m5}} \right) \quad (5)$$

where  $\left( \frac{1}{\omega L_5} \parallel \frac{1}{g_{m5}} \right)$  is the load impedance and the gain indicates a frequency-dependent voltage gain.

$$A_v = A_{v1} \times A_{v2} \quad (6)$$

QF is expressed in terms of conductance and LC,

$$Q_1 = \frac{\sqrt{L_1 + L_2}}{g_{m1}L_2} \quad (7)$$

For Power Added Efficiency (PAE),

$$PAE = \left( \frac{P_{out} - P_{in}}{P_{DC}} \right) \quad (8)$$

The circuit consists of the matching and amplifying elements of the network. The input matching network's components are  $L_1$ ,  $L_2$ , and  $C_{gs1}$ . To adjust 2<sup>nd</sup> stage to its resonant frequency,  $C_{gs2}$  and  $C_{gs3}$  are in conjunction with the inductor  $L_5$ .  $R_2$ ,  $C_1$ , and  $L_3$  are used to couple two stages. The output matching network makes the use of  $L_7$ ,  $C_2$ , and  $C_3$ . The source and load impedance have been found to be 50  $\Omega$ .

#### IV. RESULTS AND DISCUSSIONS

The design simulations were performed using Spectre RF from the Cadence design suite. To ascertain the performance analysis, have to look at the SP analysis, which primarily

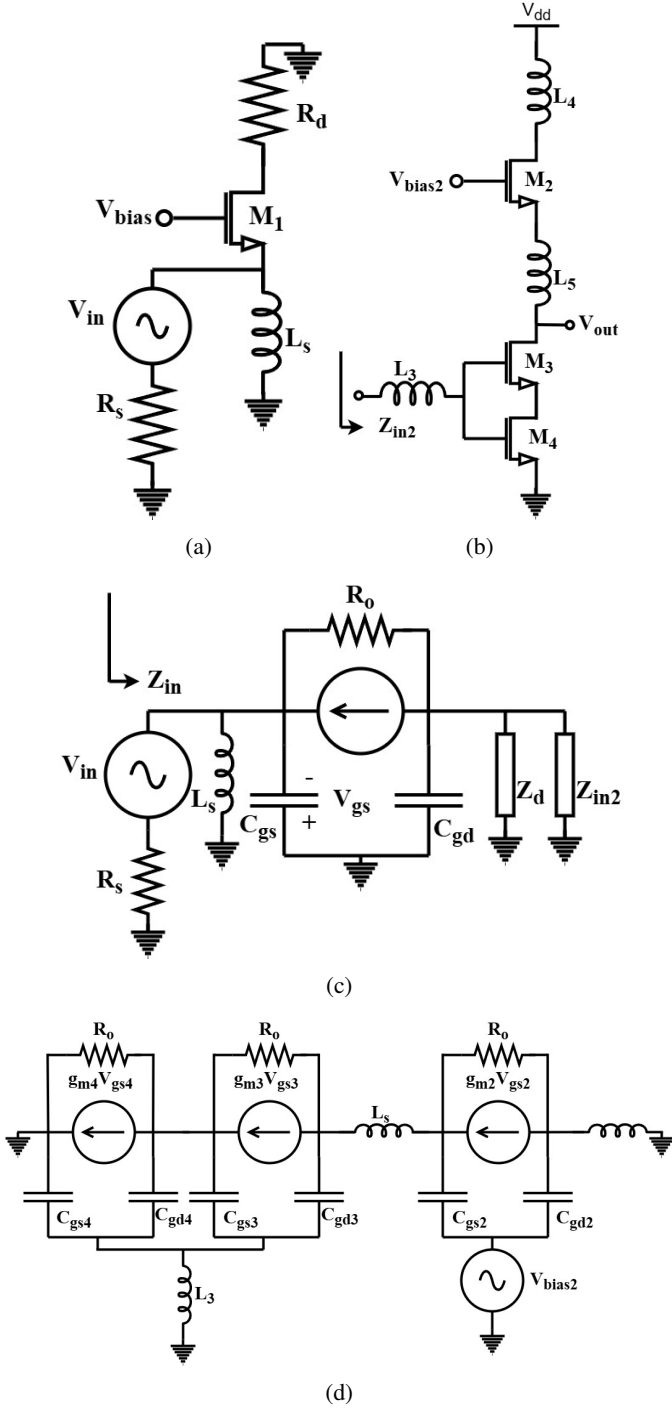


Fig. 6: (a) Configuration of a CG input stage, (b) Configuration of a CS middle stage, (c) Small signal of the CG stage, (d) Small signal of the CS stage

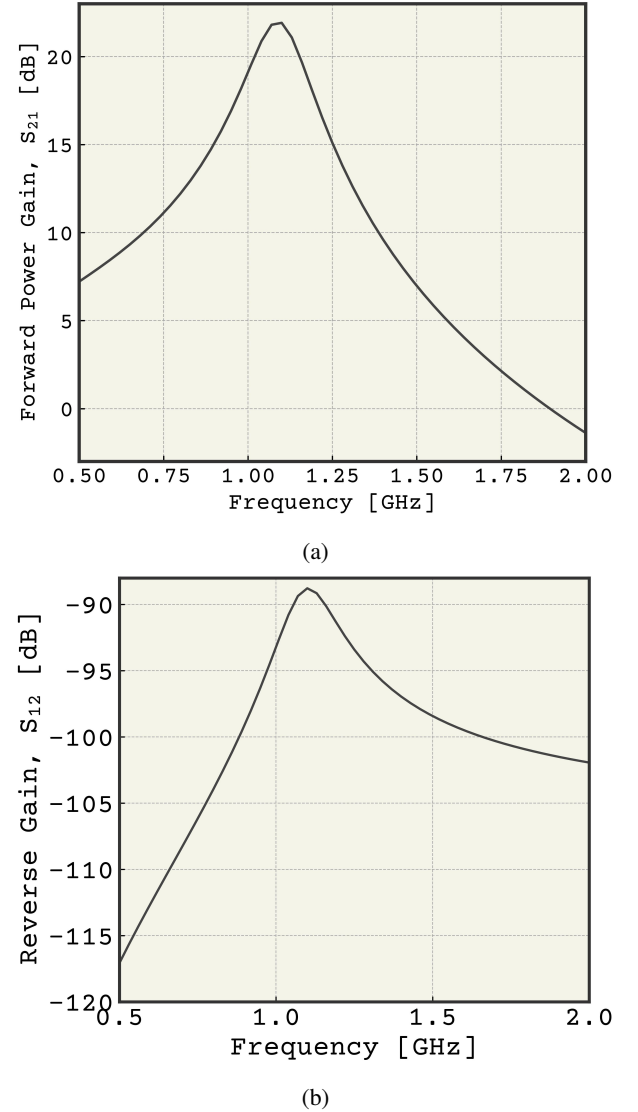


Fig. 7: (a) Forward gain, (b) Reverse gain of the proposed PA shows the circuit's performance in a chosen location. The

parameters of the SP analysis, denoted as  $S_{11}$ ,  $S_{21}$ ,  $S_{12}$ ,  $S_{22}$  and the  $k_f$ ,  $B_1$  factor allow to ascertain the circuit's stability factor and gain condition.

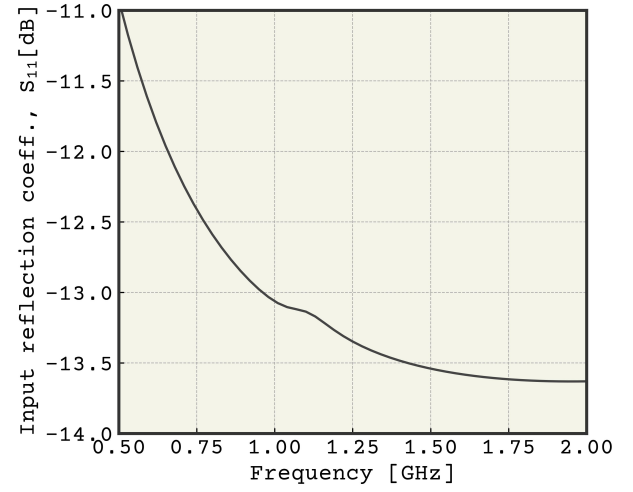
The gain curve and the isolation curve for the suggested PA simulations are both depicted in Fig.7(a)(b). The curves shows that if the frequency increases, the gain is peaking at 21.90 dB and reverse gain is -92 dB at the center frequency of 1.097 GHz. With a 1.2 V supply voltage, gain tapers to about 15 dB at the edges of the bandwidth. This gain value signifies that output power is more than hundred times amplified than input power. And the value of  $S_{12}$  means a little signal is leaking backward and the amplifier is doing a great job of blocking reverse signal flow. Adjusting  $C_1$ ,  $L_3$  and  $R_2$ , transconductance of the single stage is tuned without significantly affecting the other parameters. This allows for fine-tune the overall gain without negatively impacting other performance metrics.

TABLE II: Comparison Table

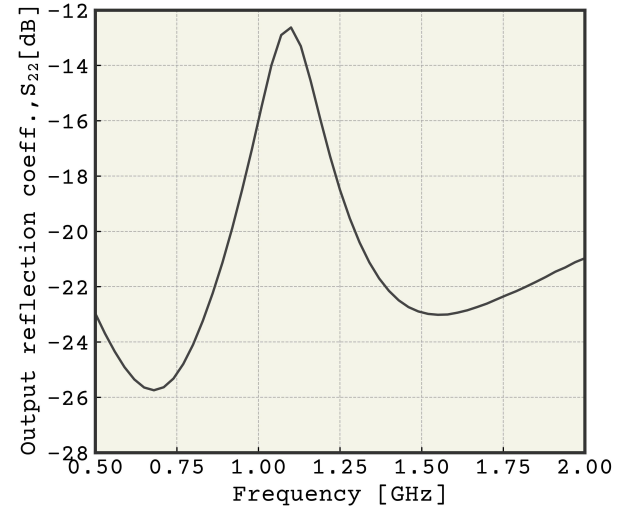
Ref.	[2]	[4]	[7]	[11]	This work
Tech. (nm)	–	180	90	180	90
Supply Voltage (V)	4	1.8	1.1	1.8	1.2
Gain (dB)	17.2	10	9.56	21.3	21.90
Bandwidth (MHz)	2050	At 2400	–	100000	350
$S_{11}$ (dB)	-10 -17	-10	–	–	-13.14
$S_{22}$ (dB)	-10 -28			–	-12.66

The simulation results for the suggested PA are shown in Fig.8(a)(b), depicting both the input reflection coefficient ( $S_{11}$ ) and output reflection coefficient ( $S_{22}$ ) curves. Here the whole bandwidth is maintained below -10 dB for both  $S_{11}$  and  $S_{22}$ , suggesting a good matching of the input and output. It indicates that most of the power is entered into the amplifier and delivered to the load and ensures minimum power loss. At the operating point, the input and output return losses are found to be -13.14 dB and -12.66 dB, respectively, where the reverse gain is - 88.84 dB. At the lower feet of bandwidth (0.9 GHz), these ( $S_{11}$ ,  $S_{22}$ ,  $S_{12}$ ) values are -12.87 dB, -20.71 dB and -99.08 dB respectively and for the higher feet (1.25 GHz), they are -13.35 dB, -18.50 dB, and -93.4 dB.

Over this bandwidth, both the stability factor,  $k_f$  and  $B_1$  follow the condition of a stable circuit. At the operating point, the value of Rollet's stability factor ( $k_f$ ) has been found to be 1kdB > 1. It implies that the designed circuit is unconditionally stable as shown in Fig.9. The Bodway stability factor has been found to be 0.992 dB. The non-zero and positive value indicates better stability characteristics in Fig.10. So the designed PA is stable.



(a)



(b)

Fig. 8: (a) Input reflection co-efficient, (b) Output reflection co-efficient of the proposed PA

The values of  $P_{out}$ ,  $P_{in}$ ,  $P_{DC}$  have been found 1.318  $\mu$ W, 0.914  $\mu$ W, and 1.993  $\mu$ W respectively, from the calculator tools of Cadence software. These reflect the linearized bias condition. PAE of 20.27 percent is found by (8) of this PA, which indicates the telemetry system operates at low power.

After performing a transient analysis in Cadence ADE to generate power waveform data over time, instantaneous power is calculated using the calculator tool. By applying the average function, an average power consumption of 153.1 mW is obtained.

The proposed PA's performance is outlined in Table-II, which compares the circuit with the reference work in terms of gain, bandwidth and impedance matching. It highlights the improvement and shows that the amplifier is competitive with or superior to contemporary implementations.

This combination of low power consumption, wideband



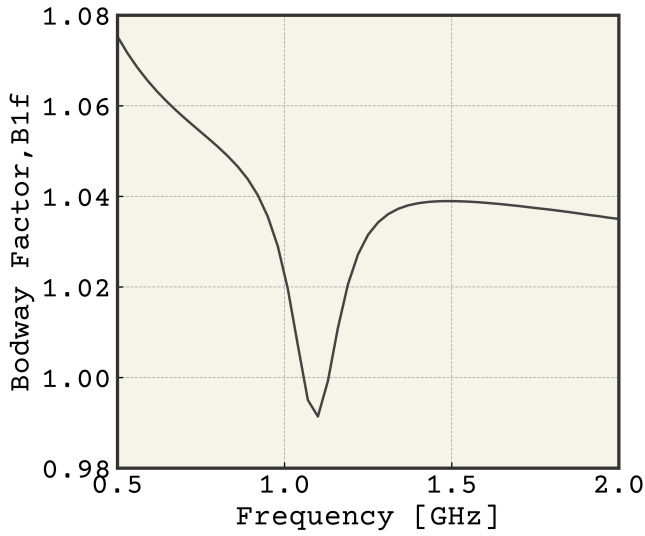


Fig. 9: Bodway ( $B_{1f}$ ) stability factor the proposed PA

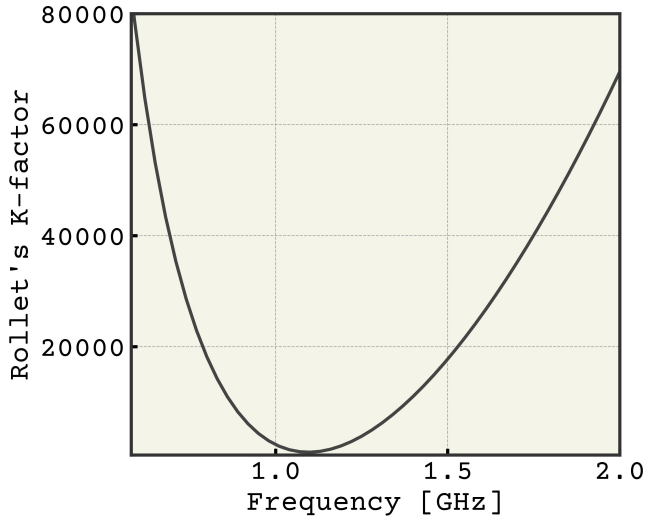


Fig. 10: Rollet's stability factor ( $k_f$ ) of the proposed PA

performance, robust gain, and assured stability makes this amplifier an ideal for compact, reliable biomedical wearables or implants. Typically, such devices require low power and high reliability to ensure patient safety, minimize heat dissipation and prolong battery life. The amplifier's stable performance supports continuous, real-time data transmission of vital signs without bulky hardware—crucial for modern healthcare solutions.

## V. CONCLUSION

In conclusion, the study looked at PA design and optimization for higher gain and bandwidth in the 0.9 GHz to 1.25 GHz frequency range. The first single-stage PA design had a lower gain and had trouble matching input impedance because of frequency-dependent transconductance and parasitic capacitance. However, the cascaded PA shows better gain

performance at a lower frequency by incorporating a second stage. To enhance impedance matching and produce greater gain and reduced return loss, matching networks were also incorporated into the design. The PA's gain, bandwidth, and matching performance were all successfully increased by the optimization efforts, meeting the necessary goals.

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